From zero Lyapunov exponents to bounded products On the occasion of the 60th birthday of Rodrigo Bamón

Jairo Bochi

Departamento de Matemática, PUC-Rio

Joint work with Andrés Navas.

Some parts joint with Artur Avila and David Damanik.

3

Cocycles

- $\Omega = \text{compact Hausdorff space}.$
- $F: \Omega \to \Omega$ continuous map.
- G =topological group (main example: $GL(\mathbb{R})$).
- $A: \Omega \to G$ continuous map.

We call A a **cocycle** over F.

Cocycles

- $\Omega = \text{compact Hausdorff space}.$
- $F: \Omega \to \Omega$ continuous map.
- G =topological group (main example: $GL(\mathbb{R})$).
- $A: \Omega \to G$ continuous map.

We call A a **cocycle** over F.

Dynamical product (non-commutative analogs of Birkhoff sums):

$$A^{(n)}(\omega) := A(F^{n-1}\omega) \cdots A(F\omega)A(\omega).$$

Cocycle relation

$$A^{(n+m)}(\omega) = A^{(m)}(F^n\omega)A^{(n)}(\omega).$$

Skew-product

If H is any space where G acts, we can define a dynamical system on $\Omega \times H$:

$$T:(\omega,p)\mapsto (F(\omega),A(\omega)\cdot p).$$

So

$$F^{n}(\omega, x) = (F^{n}(\omega)), \underbrace{A(F^{n-1}(\omega))\cdots A(F(\omega))A(\omega)}_{A^{(n)}(\omega)} \cdot p).$$

3

(日) (周) (三) (三)

Skew-product

If H is any space where G acts, we can define a dynamical system on $\Omega \times H$:

$$T:(\omega,p)\mapsto (F(\omega),A(\omega)\cdot p).$$

So

$$F^{n}(\omega, x) = (F^{n}(\omega)), \underbrace{A(F^{n-1}(\omega))\cdots A(F(\omega)))A(\omega)}_{A^{(n)}(\omega)} \cdot p).$$



Jairo Bochi (PUC-Rio)

rom zero Lyapunov exponents to bounded

Conjugacy

Two cocycles A and B (over F) are said to be **conjugate** (or **cohomologous**) if there exists a continuous map $U: \Omega \to G$ such that

$$A(\omega) = U(F\omega)B(\omega)U(\omega)^{-1}, \quad ext{for all } \omega \in \Omega.$$

Then the associated skew-products on $\Omega \times H$ are conjugate under a conjugacy $(\omega, p) \mapsto (\omega, U(\omega)p)$.

Growth of products

Take a *linear* cocycle, i.e., a cocycle with $G = GL(d, \mathbb{R})$. Let μ be an *F*-invariant probability on Ω . Lyapunov exponent:

$$L(F, A, \mu) = \lim_{n \to \infty} \frac{1}{n} \log \|A^{(n)}(\omega)\| \ge 0.$$

(The limit exists for μ -almost every ω , and is independent of ω .)

Growth of products

Take a *linear* cocycle, i.e., a cocycle with $G = GL(d, \mathbb{R})$. Let μ be an *F*-invariant probability on Ω . Lyapunov exponent:

$$L(F, A, \mu) = \lim_{n \to \infty} \frac{1}{n} \log \|A^{(n)}(\omega)\| \ge 0.$$

(The limit exists for μ -almost every ω , and is independent of ω .) We say that cocycle has **uniform subexponential growth** if

$$\forall \epsilon > 0 \; \exists C_{\epsilon} \; \text{s.t.} \; \left\| [A^{(n)}(\omega)]^{\pm 1} \right\| \leq C_{\epsilon} e^{\epsilon n} \; \forall \omega \in \Omega.$$

An equivalent condition is:

 $L(F, A, \mu) = 0$ for every invariant μ .

Growth of products

Take a *linear* cocycle, i.e., a cocycle with $G = GL(d, \mathbb{R})$. Let μ be an *F*-invariant probability on Ω . Lyapunov exponent:

$$L(F, A, \mu) = \lim_{n \to \infty} \frac{1}{n} \log \|A^{(n)}(\omega)\| \ge 0.$$

(The limit exists for μ -almost every ω , and is independent of ω .) We say that cocycle has **uniform subexponential growth** if

$$\forall \epsilon > 0 \; \exists C_{\epsilon} \; \text{s.t.} \; \left\| [A^{(n)}(\omega)]^{\pm 1} \right\| \leq C_{\epsilon} e^{\epsilon n} \; \forall \omega \in \Omega.$$

An equivalent condition is:

 $L(F, A, \mu) = 0$ for every invariant μ .

A stronger condition: The cocycle is product-bounded if

$$\exists C > 0 \text{ s.t. } \left\| [A^{(n)}(\omega)]^{\pm 1} \right\| \leq C \ \forall \omega \in \Omega.$$

A way get to product-bounded cocycles

Suppose A is conjugate to a cocycle of "rotations" $B : \Omega \to O(d, \mathbb{R})$, i.e., $\exists U$ continuous s.t.

$$A(\omega) = U(F\omega)B(\omega)U(\omega)^{-1}.$$

3

A way get to product-bounded cocycles

Suppose A is conjugate to a cocycle of "rotations" $B : \Omega \to O(d, \mathbb{R})$, i.e., $\exists U$ continuous s.t.

$$A(\omega) = U(F\omega)B(\omega)U(\omega)^{-1}.$$

Then A is obviously product-bounded, because:

$$A^{(n)}(\omega) = U(F^n \omega) B^{(n)}(\omega) U(\omega)^{-1}$$

A way get to product-bounded cocycles

Suppose A is conjugate to a cocycle of "rotations" $B : \Omega \to O(d, \mathbb{R})$, i.e., $\exists U$ continuous s.t.

$$A(\omega) = U(F\omega)B(\omega)U(\omega)^{-1}.$$

Then A is obviously product-bounded, because:

$$A^{(n)}(\omega) = U(F^n \omega) B^{(n)}(\omega) U(\omega)^{-1}.$$

Coronel–Navas–Ponce: If the dynamics F is *minimal* then the converse holds (Product-bounded \Rightarrow conjugate to rotations).

And how to get a conjugacy with rotations?

Take H = space of ellipsoids in \mathbb{R}^d (centered at the origin) There is a obvious action of $GL(d, \mathbb{R})$ on H.

(A fact to be used later: There is a Riemannian metric on H which is invariant under the action, and has sectional curvature ≤ 0 .)

And how to get a conjugacy with rotations?

Take H = space of ellipsoids in \mathbb{R}^d (centered at the origin) There is a obvious action of $GL(d, \mathbb{R})$ on H.

(A fact to be used later: There is a Riemannian metric on H which is invariant under the action, and has sectional curvature ≤ 0 .)

A matrix is a rotation iff it leaves invariant the unit ball $p_0 \in H$.

And how to get a conjugacy with rotations?

Take H = space of ellipsoids in \mathbb{R}^d (centered at the origin) There is a obvious action of $GL(d, \mathbb{R})$ on H.

(A fact to be used later: There is a Riemannian metric on H which is invariant under the action, and has sectional curvature ≤ 0 .) A matrix is a rotation iff it leaves invariant the unit ball $p_0 \in H$. Then a cocycle A is conjugate to a cocycle of rotations iff it has a *continuous invariant section* $\phi : \Omega \to H$

Invariance:
$$A(\omega) \cdot \phi(\omega) = \phi(F\omega)$$

Invariance means that the graph of ϕ is invariant under the skew-product. Proof of the "iff": conjugate to send ϕ to constant = the unit ball $\in H$.

First result

Theorem [B.-Navas]

If $A : \Omega \to GL(d, \mathbb{R})$ has uniform subexponential growth then we can perturb it in the C^0 -topology so that it becomes conjugate to a cocycle of rotations (and in particular, becomes product-bounded).

First result

Theorem [B.-Navas]

If $A : \Omega \to GL(d, \mathbb{R})$ has uniform subexponential growth then we can perturb it in the C^0 -topology so that it becomes conjugate to a cocycle of rotations (and in particular, becomes product-bounded).

Done previously by Avila–B.–Damanik for the group $SL(2,\mathbb{R})$ (with some assumptions on Ω).

Applications of this kind of result

Theorem 1 [ABD]: Genericity of Cantor spectrum

Let T be "rotation-like". For C^0 -generic potential functions $v : X \to \mathbb{R}$, the associated spectrum $\Sigma \subset \mathbb{R}$ is a **Cantor set**.

Applications of this kind of result

Theorem 1 [ABD]: Genericity of Cantor spectrum

Let T be "rotation-like". For C^0 -generic potential functions $v : X \to \mathbb{R}$, the associated spectrum $\Sigma \subset \mathbb{R}$ is a **Cantor set**.

Theorem 2 [ABD]: Denseness of uniform hyperbolicity

Let T be "rotation-like". Then the **uniformly hyperbolic** matrix maps form an **open and dense** subset of $C_0^0(X, SL(2, \mathbb{R}))$.

0 means homotopic to constant.

Applications of this kind of result

Theorem 1 [ABD]: Genericity of Cantor spectrum

Let T be "rotation-like". For C^0 -generic potential functions $v : X \to \mathbb{R}$, the associated spectrum $\Sigma \subset \mathbb{R}$ is a **Cantor set**.

Theorem 2 [ABD]: Denseness of uniform hyperbolicity

Let T be "rotation-like". Then the **uniformly hyperbolic** matrix maps form an **open and dense** subset of $C_0^0(X, SL(2, \mathbb{R}))$.

0 means homotopic to constant.

A potential application: Try to extend Theorem 2 above for d > 2, replacing uniform hyperbolicity is *projective hyperbolicity* (also called *exponential separation* or *domination*).

Another application

A theorem of B.-Viana says that for a generic linear cocycle, the Oseledets splitting is (trivial or) dominated. If the dynamics is uniquely ergodic then we can apply the fibered versions previous results to perturb the cocycle and make the action conformal in the subbundles of the dominated splitting. More precisely, we have ...

11 / 25

Another application

Theorem

Assume that $F : \Omega \to \Omega$ is uniquely ergodic with an invariant measure of full support. Then there is a dense subset \mathcal{D} of $C^0(\Omega, GL(d, \mathbb{R}))$ such that for all $A \in \mathcal{D}$ there are:

- a Riemannian metric on the vector bundle Ω × ℝ^d (that is, a continuous choice of inner product ⟨·, ·⟩_ω on each fiber {ω} × ℝ^d);
- a continuous (F, A)-invariant splitting ℝ^d = E₁(ω) ⊕ · · · ⊕ E_k(ω) which is orthogonal with respect to the Riemannian metric;
- constants c₁ > · · · > c_k > 0

such that, denoting $\|v\|_{\omega}=\sqrt{\langle v,v\rangle_{\omega}}$, we have

$$\|A(\omega)v_i\|_{T\omega} = c_i\|v_i\|_{\omega}$$
 for all $v_i \in E_i(\omega)$.

- 3

Since $GL(1, \mathbb{R}) \sim (\mathbb{R}, +)$ (take log), the case d = 1 of the B–N theorem reduces to: Baby Theorem: The one-dimensional case

Let $g: \Omega \to \mathbb{R}$ be a continuous function. If the Birkhoff averages $\frac{1}{n}g^{(n)}$ converge uniformly to zero, then there is \tilde{g} arbitrarily close to g that is a coboundary.

13 / 25

Proof of the Baby Theorem

(Idea from [CNP2].)

Define a sequence of continuous functions $\phi_N \colon \Omega \to \mathbb{R}$ by the magic formula:

$$\phi_N(\omega) = \frac{1}{N} \sum_{i=0}^{N-1} [-g^{(i)}(\omega)]$$

Proof of the Baby Theorem

(Idea from [CNP2].)

Define a sequence of continuous functions $\phi_N \colon \Omega \to \mathbb{R}$ by the *magic formula*:

$$\phi_N(\omega) = \frac{1}{N} \sum_{i=0}^{N-1} [-g^{(i)}(\omega)]$$

Then

$$\phi_N(F\omega) = \frac{1}{N} \sum_{i=0}^{N-1} [-g^{(i)}(F\omega)] = \frac{1}{N} \sum_{i=0}^{N-1} \left[-g^{(i+1)}(\omega) + g(\omega) \right]$$
$$= \phi_N(\omega) + g(\omega) + \frac{g^{(N)}(\omega)}{N}$$

Since $\frac{g^{(N)}(\omega)}{N} \to 0$ (assumption), we conclude that the sequence of coboundaries $\phi_N \circ F - \phi_N$ converges uniformly to g.

Proof of the Adult Theorem: ideas

We need to perturb A to \tilde{A} so that the associated skew-product has an invariant section of ellipsoids. Two steps:

Proof of the Adult Theorem: ideas

We need to perturb A to \tilde{A} so that the associated skew-product has an invariant section of ellipsoids. Two steps:

• First show that if A has uniform subexponential growth, then there is a sequence of "almost invariant" sections $\phi_N : \Omega \to H$; more precisely, the distance between the graph of ϕ_N and its *F*-image tends to zero as $N \to \infty$.

Proof of the Adult Theorem: ideas

We need to perturb A to \tilde{A} so that the associated skew-product has an invariant section of ellipsoids. Two steps:

- First show that if A has uniform subexponential growth, then there is a sequence of "almost invariant" sections $\phi_N : \Omega \to H$; more precisely, the distance between the graph of ϕ_N and its *F*-image tends to zero as $N \to \infty$.
- **2** Next we will show that if (F, A) has a almost invariant section ϕ , then one can perturb A so that ϕ becomes invariant.

For Step 1, the idea to construct almost invariant sections φ_N is to imitate the magic formula, replacing the averaging operation
 ¹/_N ∑^{N-1}_{i=0} by an appropriate *barycenter* concept.

- For Step 1, the idea to construct almost invariant sections φ_N is to imitate the magic formula, replacing the averaging operation
 ¹/_N ∑^{N-1}_{i=0} by an appropriate *barycenter* concept.
- In Step 2, the perturbation Ã(ω) of A(ω) is obtained by left-multiplying A(ω) by a matrix close to the identity that takes the ellipsoid A(ω)φ(ω) to the nearby ellipsoid φ(Fω).

16 / 25

- For Step 1, the idea to construct almost invariant sections φ_N is to imitate the magic formula, replacing the averaging operation
 ¹/_N ∑^{N-1}_{i=0} by an appropriate *barycenter* concept.
- In Step 2, the perturbation Ã(ω) of A(ω) is obtained by left-multiplying A(ω) by a matrix close to the identity that takes the ellipsoid A(ω)φ(ω) to the nearby ellipsoid φ(Fω). This is not as trivial as it seems, because these two ellipsoids may be very distorted, and moreover the correcting matrices must be chosen in a way that depends continuously on ω. We accomplish this by establishing a certain *uniform homogeneity* property of the space of ellipsoids.

- For Step 1, the idea to construct almost invariant sections φ_N is to imitate the magic formula, replacing the averaging operation
 ¹/_N ∑^{N-1}_{i=0} by an appropriate *barycenter* concept.
- In Step 2, the perturbation Ã(ω) of A(ω) is obtained by left-multiplying A(ω) by a matrix close to the identity that takes the ellipsoid A(ω)φ(ω) to the nearby ellipsoid φ(Fω). This is not as trivial as it seems, because these two ellipsoids may be very distorted, and moreover the correcting matrices must be chosen in a way that depends continuously on ω. We accomplish this by establishing a certain *uniform homogeneity* property of the space of ellipsoids.

The key tools, the *barycenter* and the *symmetries*, are geometric and work in more general situations...

(Rem: Both concepts were introduced by Cartan in the 1920's.)

- 4 週 1 - 4 三 1 - 4 三 1

Cocycles of isometries

H = symmetric simply-connected space of curvature ≤ 0 . (Possibly of infinite dimension.)

We consider **cocycles of isometries**, i.e. cocycles in the group Isom(H). Example: H = Poincaré disc.



A familiar example of H

Let $\mathbb{H} = \{x + iy \in \mathbb{C}; y > 0\}$ be the hyperbolic half-space; Riemannian metric $ds^2 = (dx^2 + dy^2)/y^2$.

The group $SL(2,\mathbb{R})$ acts on \mathbb{H} by isometries:

$$A = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \Rightarrow \phi_A(z) = \frac{az+b}{cz+d}$$

18 / 25

A familiar example of H

Let $\mathbb{H} = \{x + iy \in \mathbb{C}; y > 0\}$ be the hyperbolic half-space; Riemannian metric $ds^2 = (dx^2 + dy^2)/y^2$.

The group $SL(2, \mathbb{R})$ acts on \mathbb{H} by isometries:

$$A = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \Rightarrow \phi_A(z) = \frac{az+b}{cz+d}$$

 $SL(2,\mathbb{R})$ also acts on the hyperbolic disk $\mathbb{D} = \{z \in \mathbb{C}; |z| < 1\}$: conjugate the previous action with a Möbius map that takes \mathbb{H} to \mathbb{D} .

The dynamics of an isometry (\neq id) looks like one of these:



Drift

Back to cocycles of isometries: $F : \Omega \to \Omega$, $A : \Omega \to \text{Isom}(H)$. Analogue of the (upper) Lyapunov exponent:

$$drift(F,A) = \lim_{n \to \infty} \frac{1}{n} dist(A^{(n)}(x) \cdot p_0, p_0)$$

(a measure of the speed the orbits approach ∂H .)

 \exists generalization of Oseledets Theorem to this context (Kaimanovich, Karlsson, Margulis, Ledrappier).

Theorem [B.-Navas]

Given a cocycle of isometries $A : \Omega \to \text{Isom}(H)$ (over a dynamics $T : \Omega \to \Omega$) with sublinear drift to infinity, we can perturb it to create an invariant section $\phi : \Omega \to H$. In particular, the perturbed cocycle has bounded orbits.

20 / 25

Theorem [B.-Navas]

Given a cocycle of isometries $A : \Omega \to \text{Isom}(H)$ (over a dynamics $T : \Omega \to \Omega$) with sublinear drift to infinity, we can perturb it to create an invariant section $\phi : \Omega \to H$. In particular, the perturbed cocycle has bounded orbits.

Remarks:

() \exists similar theorem for continuous-time dynamical systems.

Theorem [B.-Navas]

Given a cocycle of isometries $A : \Omega \to \text{Isom}(H)$ (over a dynamics $T : \Omega \to \Omega$) with sublinear drift to infinity, we can perturb it to create an invariant section $\phi : \Omega \to H$. In particular, the perturbed cocycle has bounded orbits.

Remarks:

- **(**) \exists similar theorem for continuous-time dynamical systems.
- ∃ a non-perturbative result on the existence of section of nearly minimal displacement. The hypotheses are weaker (Buseman, CAT(0), ...)

Theorem [B.-Navas]

Given a cocycle of isometries $A : \Omega \to \text{Isom}(H)$ (over a dynamics $T : \Omega \to \Omega$) with sublinear drift to infinity, we can perturb it to create an invariant section $\phi : \Omega \to H$. In particular, the perturbed cocycle has bounded orbits.

Remarks:

- **(**) \exists similar theorem for continuous-time dynamical systems.
- ∃ a non-perturbative result on the existence of section of nearly minimal displacement. The hypotheses are weaker (Buseman, CAT(0), ...)
- Solution ⇒ 3 versions of these result for other fiber bundles (≠ Ω × H). (Those are actually needed in our application.)

First tool: barycenter

The Cartan barycenter of a list of points p_1, \ldots, p_n is the unique point that minimizes the function:

$$x\mapsto \sum_{i=1}^n d(x,p_i)^2.$$

(Works globally with our assumptions on H)

The barycenter is obviously equivariant under isometries.

First tool: barycenter

The Cartan barycenter of a list of points p_1, \ldots, p_n is the unique point that minimizes the function:

$$x\mapsto \sum_{i=1}^n d(x,p_i)^2.$$

(Works globally with our assumptions on H)

The barycenter is obviously equivariant under isometries. "Lipschitzness" property:

$$d(\mathsf{bar}\{p_i\},\mathsf{bar}\{q_i\}) \leq rac{1}{n}\sum_{i=1}^n d(p_i,q_i).$$

21 / 25

Step 1: The magic formula for the almost-invariant section



Uniform homogeneity of H

To perform Step 2 of the proof of the Main Theorem (the closing of the almost-invariant section), we use the following:

Lemma (Macroscopic uniform homogeneity)

There exists a continuous map $J : H \times H \rightarrow \text{lsom}(H)$ with the following properties:

- J(p,q)p = q for all $p, q \in H$.
- I(p, q) converges uniformly on bounded sets of H to the identity as the distance between p and q converges to zero.

Uniform homogeneity of H

To perform Step 2 of the proof of the Main Theorem (the closing of the almost-invariant section), we use the following:

Lemma (Macroscopic uniform homogeneity)

There exists a continuous map $J : H \times H \rightarrow \text{lsom}(H)$ with the following properties:

•
$$J(p,q)p = q$$
 for all $p, q \in H$.

I(p, q) converges uniformly on bounded sets of H to the identity as the distance between p and q converges to zero.

More explicitly, assertion 2 means:

 $\forall \epsilon > 0 \ \forall B \subset H$ bounded $\exists \delta > 0$ such that

 $p,q \in H, d(p,q) < \delta \Rightarrow d(J(p,q)r,r) < \epsilon \ \forall r \in B.$

(Notice that p and q are not restricted to a bounded set; that is essentially what makes the lemma non-trivial.)

Jairo Bochi (PUC-Rio)

Proof of the uniform homogeneity lemma

For any $p \in H$, let $\sigma_p : H \to H$ denote the Cartan symmetry around p. We want to continuously define a isometry J(p, q) that takes p to q and moves the base-point p_0 as little as possible.

Proof of the uniform homogeneity lemma

For any $p \in H$, let $\sigma_p : H \to H$ denote the Cartan symmetry around p. We want to continuously define a isometry J(p,q) that takes p to q and moves the base-point p_0 as little as possible.



m is the midpoint of *q* and $\sigma_{p_0}(p)$. The isometry $J(p, q) := \sigma_m \circ \sigma_{p_0}$ sends *p* to *q* and translates the geodesic joining p_0 and *m* by length $2\text{dist}(p_0, m)$, which by nonpositive curvature is $\leq \text{dist}(p, q)$.

Thank you!

Happy birthday, Rodrigo!

イロト イポト イヨト イヨト