Sharp solvability criteria for Dirichlet problems of mean curvature type in Riemannian manifolds: non-existence results

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Abstract

It is well known that the Serrin condition is a necessary condition for the solvability of the Dirichlet problem for the prescribed mean curvature equation in bounded domains of \mathbb{R}^n with certain regularity. In this paper we investigate this fact for the vertical mean curvature equation in the product $M^n \times \mathbb{R}$. Precisely, given a \mathscr{C}^2 bounded domain Ω in M and a function H = H(x, z) continuous in $\overline{\Omega} \times \mathbb{R}$ and non-decreasing in the variable z, we prove that the strong Serrin condition $(n-1)\mathcal{H}_{\partial\Omega}(y) \geq n \sup_{\Omega \to 0} |H(y, z)| \quad \forall y \in \partial\Omega$, is a necessary condition for the solvability of the

 $z\in\mathbb{R}$ Dirichlet problem in a large class of Riemannian manifolds within which are the Hadamard manifolds and manifolds whose sectional curvatures are bounded above by a positive constant. As a consequence of our results we deduce Jenkins-Serrin and Serrin type sharp solvability criteria.

1 Introduction

We denote by M a complete Riemannian manifold of dimension $n \ge 2$ and let Ω be a domain in M. The focus of our work is the prescribed mean curvature equation for vertical graphs in $M \times \mathbb{R}$, this is,

$$\mathcal{M}u := \operatorname{div}\left(\frac{\nabla u}{W}\right) = nH(x, u),$$
(1)

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where *H* is a continuous function over $\overline{\Omega} \times \mathbb{R}$ and non-decreasing in the variable $z, W = \sqrt{1 + \|\nabla u(x)\|^2}$ and the quantities involved are calculated with respect to the metric of *M*. In a coordinates system (x_1, \ldots, x_n) in *M*, it follows that

$$\mathcal{M}u = \frac{1}{W} \sum_{i,j=1}^{n} \left(\sigma^{ij} - \frac{u^i u^j}{W^2} \right) \nabla_{ij}^2 u = nH(x, u), \tag{2}$$

where (σ^{ij}) is the inverse of the metric (σ_{ij}) of M, $u^i = \sum_{j=1}^n \sigma^{ij} \partial_j u$ are the

coordinates of ∇u and $\nabla_{ij}^2 u(x) = \nabla^2 u(x) \left(\frac{\partial}{\partial x_i}, \frac{\partial}{\partial x_j}\right)$. We will denote by \mathfrak{Q} the operator defined by

$$\mathfrak{Q}u = \mathcal{M}u - nH(x, u).$$

We notice that the matrix of the operator \mathcal{M} is given by $A = \frac{1}{W}g$, where g is the induce metric on the graph of u. This implies that the eigenvalues of A are positive and depends on x and on ∇u . Hence, \mathcal{M} is locally uniformly elliptic. Furthermore, if Ω is bounded and $u \in \mathscr{C}^1(\overline{\Omega})$, then \mathcal{M} is uniformly elliptic in $\overline{\Omega}$ (see [19] for more details).

It has been proved in chronological order by Finn [9], Jenkins-Serrin [14] and Serrin [18], that the very well known Serrin condition is a necessary condition for the solvability of the Dirichlet problem for equation (1) in bounded domains of \mathbb{R}^{n} .

Dirichlet problems for equations whose solutions describe hypersurfaces of prescribed mean curvature has been also studied outside of the Euclidean space. Several works have considered a Serrin type condition that provides some existence theorem in their respective context (see [1], [2], [7], [8], [13], [16], [17] and [19] as examples). However, non-existence theorem has been only investigated in a few cases that we summarize below.

For instance, P.-A Nitsche [17] was concerned with graph-like prescribed mean curvature hypersurfaces in hyperbolic space \mathbb{H}^{n+1} . In the half-space setting, he studied radial graphs over the totally geodesic hypersurface $S = \{x \in \mathbb{R}^{n+1}; (x_0)^2 + \cdots + (x_n)^2 = 1\}$. He established an existence result if Ω is a bounded domain of S of class $\mathscr{C}^{2,\alpha}$ and $H \in \mathscr{C}^1(\overline{\Omega})$ is a function satisfying $\sup |H| \leq 1$ and $|H(y)| < \mathcal{H}_C(y)$ everywhere on $\partial\Omega$, where \mathcal{H}_C denotes the hyperbolic mean curvature of the cylinder C over $\partial\Omega$. Furthermore he showed the existence of smooth boundary data such that no solution exists in case of $|H(y)| > \mathcal{H}_C(y)$ for some $y \in \partial\Omega$ under the assumption that H has a sign. We observe that his results does not provide Serrin type solvability criterion.

Also, E. M. Guio-R. Sa Earp [12, 13] considered a bounded domain Ω contained in a vertical totally geodesic hyperplane P of \mathbb{H}^{n+1} and studied the Dirichlet problem for the mean curvature equation for horizontal graphs over Ω , that is, hypersurfaces which intersect at most only once the horizontal horocycles orthogonal to Ω . They considered the hyperbolic cylinder C generated by horocycles cutting ortogonally P along the boundary of Ω and the Serrin condition, $\mathcal{H}_C(y) \ge |H(y)| \forall y \in \partial \Omega$. They obtained a Serrin type solvability criterion for prescribed mean curvature H = H(x) and also proved a sharp solvability criterion for constant H.

Finally, M. Telichevesky [20, Th. 6 p. 246] proved that if M is a Hadamard manifold having -1 as an upper bound for the sectional curvature, then mean convexity is a necessary condition for the existence of a vertical minimal graphs in $M \times \mathbb{R}$ over a domain Ω of M possibly unbounded. This result combined with an existence result of Aiolfi-Ripoll-Soret [1, Th. 1 p. 72] gives sharp solvability criterion for the minimal hypersurface equation in bounded domains of M.

To the best of our knowledge, no other Serrin-type solvability criterion has been proved outside of the Euclidean setting.

In this paper we generalize the aforementioned non-existence result in the $M \times \mathbb{R}$ context. More precisely, we prove the following¹:

Theorem 1 (main theorem). Let $\Omega \subset M$ be a bounded domain whose boundary is of class \mathscr{C}^2 . Let $H \in \mathscr{C}^0(\overline{\Omega} \times \mathbb{R})$ be a function either non-positive or non-negative and non-decreasing in the variable z. Let us assume that there exists $y_0 \in \partial \Omega$ such that

$$(n-1)\mathcal{H}_{\partial\Omega}(y_0) < n \sup_{z \in \mathbb{R}} |H(y_0, z)|.$$

Suppose also that $\operatorname{cut}(y_0) \cap \Omega = \emptyset$. Furthermore, assume that the radial curvature over the radial geodesics issuing from y_0 and intersecting Ω is bounded above by K_0 , where

(a) $K_0 \leq 0$, or

(b)
$$K_0 > 0$$
 and $\operatorname{dist}(y_0, x) < \frac{\pi}{2\sqrt{K_0}}$ for all $x \in \overline{\Omega}$.

Then there exists $\varphi \in \mathscr{C}^{\infty}(\overline{\Omega})$ such that there is no $u \in \mathscr{C}^{0}(\overline{\Omega}) \cap \mathscr{C}^{2}(\Omega)$ satisfying equation (1) with $u = \varphi$ in $\partial \Omega$.

The statement ensures that the strong Serrin condition

$$(n-1)\mathcal{H}_{\partial\Omega}(y) \ge n \sup_{z \in \mathbb{R}} |H(y,z)| \ \forall \ y \in \partial\Omega$$
(3)

is a necessary condition for the solvability of the Dirichlet problem for equation (1).

Some direct consequences inferred from our main non-existence theorem are stated as follows.

Corollary 2. Let M be a Cartan-Hadamard manifold and $\Omega \subset M$ a bounded domain whose boundary is of class \mathscr{C}^2 . Let $H \in \mathscr{C}^0(\overline{\Omega} \times \mathbb{R})$ be a function either

¹For the definition of radial curvature we refer that from Greene-Wu [11, p. 5]. We denote by $\operatorname{cut}(y_0)$ the *cut locus* of y_0 .

non-negative or non-positive and non-decreasing in the variable z. Suppose there exists $y_0 \in \partial \Omega$ such that

$$(n-1)\mathcal{H}_{\partial\Omega}(y_0) < n \sup_{z \in \mathbb{R}} |H(y_0, z)|$$

Then there exists $\varphi \in \mathscr{C}^{\infty}(\overline{\Omega})$ such that there is no $u \in \mathscr{C}^{0}(\overline{\Omega}) \cap \mathscr{C}^{2}(\Omega)$ satisfying equation (1) with $u = \varphi$ in $\partial \Omega$.

Corollary 3. Let M be a simply connected and compact manifold whose sectional curvature satisfies $\frac{1}{4}K_0 < K \leq K_0$ for a positive constant K_0 . Let $\Omega \subset M$ be a domain with diam $(\Omega) < \frac{\pi}{2\sqrt{K_0}}$ and whose boundary is of class \mathscr{C}^2 . Let $H \in \mathscr{C}^0(\overline{\Omega} \times \mathbb{R})$ be a function either non-negative or non-positive and nondecreasing in the variable z. Suppose there exists $y_0 \in \partial\Omega$ such that

$$(n-1)\mathcal{H}_{\partial\Omega}(y_0) < n \sup_{z \in \mathbb{R}} |H(y_0, z)|.$$

Then there exists $\varphi \in \mathscr{C}^{\infty}(\overline{\Omega})$ such that there is no $u \in \mathscr{C}^{0}(\overline{\Omega}) \cap \mathscr{C}^{2}(\Omega)$ satisfying equation (1) with $u = \varphi$ in $\partial \Omega$.

We remark that the assumption in the above statement guarantees that the injectivity radius of M is greater than $\frac{\pi}{2\sqrt{K_0}}$.

2 Sharp solvability criteria

We now want to highlight Serrin type solvability criteria derived from the combination of our non-existence results with existence results obtained by others [19, 1] and by the authors [3, 4].

Firstly, we observe that the combination of corollary 2 with the existence theorem from Aiolfi-Ripoll-Soret [1, Th. 1 p. 72] for the minimal case shows that the sharp solvability criterion of Jenkins-Serrin [14, Th. 1 p. 171] also holds in Cartan-Hadamard manifolds:

Theorem 4 (Sharp Jenkins-Serrin-type solvability criterion). Let M be a Cartan-Hadamard manifold and $\Omega \subset M$ a bounded domain whose boundary is of class $\mathscr{C}^{2,\alpha}$ for some $\alpha \in (0,1)$. Then the Dirichlet problem for equation $\mathcal{M}u = 0$ in Ω has a unique solution for arbitrary continuous boundary data if, and only if, Ω is mean convex.

Secondly, combining corollary 3 with the existence result of Spruck [19, Th. 1.4 p. 787] we infer the following:

Theorem 5 (Sharp Serrin-type solvability criterion). Let M be a simply connected and compact manifold whose sectional curvature satisfies $\frac{1}{4}K_0 < K \leq K_0$ for a positive constant K_0 . Let $\Omega \subset M$ be a domain with diam $(\Omega) < \frac{\pi}{2\sqrt{K_0}}$ and whose boundary is of class $\mathscr{C}^{2,\alpha}$ for some $\alpha \in (0,1)$. Then the Dirichlet problem for equation (1) in Ω has a unique solution for every constant H and arbitrary continuous boundary data if, and only if, $(n-1)\mathcal{H}_{\partial\Omega} \geq n |H|$.

Notice that it was not established in every Cartan-Hadamard manifold a sharp Serrin type result [18, p. 416] for arbitrary constant H. For example, if $M = \mathbb{H}^n$, it follows from the existence result of Spruck [19, Th. 1.4 p. 787] that the Serrin condition is a sufficient condition if $H \geq \frac{n-1}{n}$. In the opposite case $0 < H < \frac{n-1}{n}$, Spruck noted that it was possible to establish an existence result if the strict inequality $(n-1)\mathcal{H}_{\partial\Omega} > nH$ holds. He used the entire graphs of constant mean curvature $\frac{n-1}{n}$ in $\mathbb{H}^n \times \mathbb{R}$ as barriers (see [5] for explicit formulas). However, this restriction over the Serrin condition in the last case does not allow to establish Serrin type solvability criterion for every constant H directly from the existence result of Spruck [19, Th. 5.4 p. 797] when the ambient is the hyperbolic space.

We have established an existence result [4, 3, Th. 4.4 p. 51] for prescribed $H \in \mathscr{C}^{1,\alpha}(\overline{\Omega} \times \mathbb{R})$ which extends the existence result of Spruck. We have the following Serrin type solvability criterion:

Theorem 6 (Serrin type solvability criterion 1). Let $\Omega \subset \mathbb{H}^n$ be a bounded domain with $\partial\Omega$ of class $\mathscr{C}^{2,\alpha}$ for some $\alpha \in (0,1)$. Let $H \in \mathscr{C}^{1,\alpha}(\overline{\Omega} \times \mathbb{R})$ be a function satisfying $\partial_z H \geq 0$ e $0 \leq H \leq \frac{n-1}{n}$ em $\Omega \times \mathbb{R}$. Then the Dirichlet problem for equation (1) has a unique solution $u \in \mathscr{C}^{2,\alpha}(\overline{\Omega})$ for every $\varphi \in$ $\mathscr{C}^{2,\alpha}(\overline{\Omega})$ if, and only if, the strong Serrin condition (3) holds.

By combining the existence result of Spruck [19, Th. 1.4 p. 787] with corollary 2, and putting together theorem 6, we deduce that the sharp solvability criterion of Serrin [18, p. 416] for arbitrary constant H also holds in the $\mathscr{C}^{2,\alpha}$ class if we replace \mathbb{R}^n for \mathbb{H}^n :

Theorem 7 (Sharp Serrin type solvability criterion). Let $\Omega \subset \mathbb{H}^n$ be a bounded domain whose boundary is of class $\mathscr{C}^{2,\alpha}$. Then the Dirichlet problem for equation (1) has a unique solution for every constant H and for arbitrary continuous boundary data if, and only if, $(n-1)\mathcal{H}_{\partial\Omega}(y) \geq n |H|$.

We have also proved [4, 3, Th. 4.1 p. 40] a generalization of an existence result of Spruck [19, Th. 1.4 p. 787] for constant mean curvature. That is, under certain regularity for $\partial\Omega$ and the boundary data φ , if the function Hsatisfies

$$\operatorname{Ricc}_{x} \ge n \sup_{z \in \mathbb{R}} \left\| \nabla_{x} H(x, z) \right\| - \frac{n^{2}}{n-1} \inf_{z \in \mathbb{R}} \left(H(x, z) \right)^{2}, \ \forall \ x \in \Omega,$$
(4)

in addition to the strong Serrin condition (3), then the Dirichlet problem for equation (1) is solvable for arbitrary boundary data sufficient smooth. This result in combination with corollary 2 yields the following generalization in the $\mathscr{C}^{2,\alpha}$ class of a theorem of Serrin [18, Th. p. 484] in the Euclidean space:

Theorem 8 (Serrin type solvability criterion 2). Let M be a Cartan-Hadamard manifold and $\Omega \subset M$ a bounded domain whose boundary is of class $\mathscr{C}^{2,\alpha}$ for some $\alpha \in (0,1)$. Suppose that $H \in \mathscr{C}^{1,\alpha}(\overline{\Omega} \times \mathbb{R})$ is either non-negative or non-positive in $\overline{\Omega} \times \mathbb{R}$, $\partial_z H \ge 0$ and

$$\operatorname{Ricc}_{x} \geq n \sup_{z \in \mathbb{R}} \left\| \nabla_{x} H(x, z) \right\| - \frac{n^{2}}{n-1} \inf_{z \in \mathbb{R}} \left(H(x, z) \right)^{2}, \ \forall \ x \in \Omega.$$

Then the Dirichlet problem for equation (1) has a unique solution $u \in \mathscr{C}^{2,\alpha}(\overline{\Omega})$ for every $\varphi \in \mathscr{C}^{2,\alpha}(\overline{\Omega})$ if, and only if, the strong Serrin condition (3) holds.

Finally, using corollary 3 we also obtain:

Theorem 9 (Serrin type solvability criterion 3). Let M be a complete and compact manifold whose sectional curvature satisfies $\frac{1}{4}K_0 < K \leq K_0$ for a positive constant K_0 . Let $\Omega \subset M$ be a domain with diam $(\Omega) < \frac{\pi}{2\sqrt{K_0}}$ and whose boundary is of class $\mathscr{C}^{2,\alpha}$ for some $\alpha \in (0, 1)$. Suppose that $H \in \mathscr{C}^{1,\alpha}(\overline{\Omega} \times \mathbb{R})$ is either non-negative or non-positive in $\overline{\Omega} \times \mathbb{R}$, $\partial_z H \geq 0$ and

$$\operatorname{Ricc}_{x} \geq n \sup_{z \in \mathbb{R}} \left\| \nabla_{x} H(x, z) \right\| - \frac{n^{2}}{n-1} \inf_{z \in \mathbb{R}} \left(H(x, z) \right)^{2}, \ \forall \ x \in \Omega.$$

Then the Dirichlet problem for equation (1) has a unique solution $u \in \mathscr{C}^{2,\alpha}(\overline{\Omega})$ for every $\varphi \in \mathscr{C}^{2,\alpha}(\overline{\Omega})$ if, and only if, the strong Serrin condition (3) holds.

3 Proof of the main non-existence theorem

The proof of theorem 1 is based in two results that will be proved in the sequel. The following fundamental proposition can trace its roots back to the work of Finn [9, Lemma p. 139] when he established the theorem ensuring the non-existence of solutions for Dirichlet problems for the minimal surface equation in non-convex domain of \mathbb{R}^2 . His lemma was extended by Jenkins-Serrin [14, Prop. III p. 182] for the minimal hypersurface equation in \mathbb{R}^n , and subsequently by Serrin [18, Th. 1 p. 459] for quasilinear elliptic operators (see also [10, Th. 14.10 p. 347]). Afterward M. Telichevesky [20, Lemma. 11 p. 250] extended the result for the minimal vertical equation in $M \times \mathbb{R}$. We will use some of the ideas of these works.

Proposition 10. Let $\Omega \in M$ a bounded domain. Let Γ' be a relative open portion of $\partial\Omega$ of class \mathscr{C}^1 . Let $H(x, z) \in \mathscr{C}^0(\overline{\Omega} \times \mathbb{R})$ be a function non-decreasing in the variable z. Let $u \in \mathscr{C}^2(\Omega) \cap \mathscr{C}^1(\Omega \cup \Gamma') \cap \mathscr{C}^0(\overline{\Omega})$ and $v \in \mathscr{C}^2(\Omega) \cap \mathscr{C}^0(\overline{\Omega})$ satisfying

$$\left\{ \begin{array}{ll} \mathfrak{Q} u \geq \mathfrak{Q} v & in \ \Omega, \\ u \leq v & in \ \partial \Omega \setminus \Gamma', \\ \frac{\partial v}{\partial N} = -\infty & in \ \Gamma', \end{array} \right.$$

where N is the inner normal to Γ' . Under these conditions $u \leq v$ in Γ' . Therefore $u \leq v$ em Ω . *Proof.* By way of contradiction, suppose that $m = \max_{\Gamma'}(u-v) > 0$. Hence, $u \leq v + m \text{ em } \Gamma'$. Then $u \leq v + m$ in $\partial \Omega$ since $u \leq v$ in $\partial \Omega \setminus \Gamma'$ by hypotheses. In view of the function H is non-decreasing in z and m > 0, we have

$$\mathfrak{Q}(v+m) = \mathcal{M}(v+m) - nH(x,v+m) \le \mathcal{M}v - nH(x,v) = \mathfrak{Q}v \le \mathfrak{Q}u.$$

As a consequence of the maximum principle (see [10, Th. 10.1 p. 263]) $u \leq v+m$ in Ω . Let $y_0 \in \Gamma'$ be such that $m = u(y_0) - v(y_0)$. Let $\gamma_{y_0} = \exp_{y_0}(tN_{y_0})$, for t > 0 near 0. Then

$$u(\gamma_{y_0}(t)) - u(y_0) \le (v(\gamma_{y_0}(t)) + m) - (v(y_0) + m) = v(\gamma_{y_0}(t)) - v(y_0).$$

Dividing the expression by t and passing to the limit as t goes to zero it follows that $\frac{\partial u}{\partial N} \leq -\infty$. This is a contradiction since $u \in \mathscr{C}^1(\Gamma')$, hence, $u \leq v$ in Γ' .

The next lemma plays a fundamental role in this paper. In this lemma we establish a height a priori estimate for solutions of equation $\mathcal{M}u = nH(x, u)$ in Ω in those points of $\partial\Omega$ on which the strong Serrin condition (3) fails.

Lemma 11. Let $\Omega \subset M$ be a bounded domain whose boundary is of class \mathscr{C}^2 . Let $H \in \mathscr{C}^0(\overline{\Omega} \times \mathbb{R})$ be a non-negative function and non-decreasing in the variable z, and $u \in \mathscr{C}^2(\Omega) \cap \mathscr{C}^0(\overline{\Omega})$ satisfying $\mathcal{M}u = nH(x, u)$. Let us assume that there exists $y_0 \in \partial\Omega$ such that

$$(n-1)\mathcal{H}_{\partial\Omega}(y_0) < nH(y_0,k) \tag{5}$$

for some $k \in \mathbb{R}$. Suppose also that $\operatorname{cut}(y_0) \cap \Omega = \emptyset$. Furthermore, assume that the radial curvature over the radial geodesics issuing from y_0 and intersecting Ω is bounded above by K_0 , where

- (a) $K_0 \leq 0$, or
- (b) $K_0 > 0$ and $\operatorname{dist}(y_0, x) < \frac{\pi}{2\sqrt{K_0}}$ for all $x \in \overline{\Omega}$.

Then for each $\varepsilon > 0$ there exists a > 0 depending only on ε , $\mathcal{H}_{\partial\Omega}(y_0)$, the geometry of Ω and the modulus of continuity of H(x,k) in y_0 , such that

$$u(y_0) < \max\left\{k, \sup_{\partial \Omega \setminus B_a(y_0)} u\right\} + \varepsilon.$$
(6)

Proof. We proceed the proof in two steps. Firstly, we will find an estimate for $u(y_0)$ depending on k and $\sup_{\partial B_a(y_0)\cap\Omega} u$ for some a that does not depend on u. Secondly, we will get an upper bound for $\sup_{a \in U} u$ in terms of $\sup_{a \in U} u$.

econdry, we will get an upper bound for
$$\sup_{\partial B_a(y_0) \cap \Omega} u$$
 in terms of $\sup_{\partial \Omega \setminus B_a(y_0)} u$.

Step 1.

First of all note that from (5) there exists $\nu > 0$ such that

$$(n-1)\mathcal{H}_{\partial\Omega}(y_0) < nH(y_0,k) - 4\nu.$$
(7)

Let $R_1 > 0$ be such that $\partial B_{R_1}(y_0) \cap \Omega$ is connected and

$$|H(x,k) - H(y_0,k)| < \frac{\nu}{n}, \ \forall \ x \in B_{R_1}(y_0) \cap \Omega.$$
(8)

Note also that we can construct an embedded and oriented hypersurface S, tangent to $\partial\Omega$ at y_0 and whose mean curvature with respect to the normal pointing inwards Ω at y_0 satisfies

$$\mathcal{H}_{\partial\Omega}(y_0) < \mathcal{H}_S(y_0) < \mathcal{H}_{\partial\Omega}(y_0) + \frac{\nu}{(n-1)}.$$
(9)

We know that for some $\tau > 0$ the map

is a diffeomorphism for each $0 \le t < \tau$, and so $S_t := \Phi_t(S)$ is parallel to S.

Let us consider the distance function $d(x) = {\rm dist}(x,S).$ Let $0 < R_2 < \min\{\tau,R_1\}$ be such that

$$|\Delta d(x) - \Delta d(y_0)| < \nu \ \forall \ x \in B_{R_2}(y_0) \cap \Omega.$$

$$\tag{10}$$

We now fix $a < R_2$. For $0 < \epsilon < a$ we set

$$\Omega_{\epsilon} = \{ x \in B_a(y_0) \cap \Omega; d(x) > \epsilon \}.$$

We choose $\phi \in \mathscr{C}^2(\epsilon, a)$ satisfying

P1.
$$\phi(a) = 0$$
, P2. $\phi' \le 0$, P3. $\phi'' \ge 0$, P4. $\phi'(\epsilon) = -\infty$.

We also require that $\phi'^3 \nu + \phi'' = 0$ in (ϵ, a) . Let $v = \max\left\{k, \sup_{\partial B_a(y_0) \cap \Omega} u\right\} + \phi \circ d$.

So, $v \ge u$ in $\partial \Omega_{\epsilon} \setminus S_{\epsilon}$. In addition, if N is the normal to S_{ϵ} inwards Ω_{ϵ} and $x \in S_{\epsilon} \cap B_a(y_0)$, then

$$\frac{\partial v}{\partial N}(x) = \langle \nabla v(x), N \rangle = \langle \phi'(d(x)) \nabla d(x), \nabla d(x) \rangle = \phi'(\epsilon) = -\infty.$$

Let us fix $x \in \Omega_{\epsilon}$. A straightforward computation yields

$$\mathfrak{Q}v = \frac{\phi'}{(1+\phi'^2)^{1/2}}\Delta d + \frac{\phi''}{(1+\phi'^2)^{3/2}} - nH(x,v).$$

Since $v \ge k$ and H is non-decreasing in z it follows that $H(x,v) \ge H(x,k)$. Hence,

$$\mathfrak{Q}v \le rac{\phi'}{(1+\phi'^2)^{1/2}}\Delta d + rac{\phi''}{(1+\phi'^2)^{3/2}} - nH(x,k).$$

By means of the properties of ϕ we have

$$\frac{\phi'}{(1+\phi'^2)^{1/2}} > -1,$$

and by the assumption on the sign of H we obtain

$$-nH(x,k) < nH(x,k)\frac{\phi'}{(1+\phi'^2)^{1/2}}.$$

Therefore,

$$\mathfrak{Q}v < \frac{\phi'}{(1+\phi'^2)^{1/2}} \left(\Delta d(x) + nH(x,k)\right) + \frac{\phi''}{(1+\phi'^2)^{3/2}}.$$
 (11)

Furthermore,

$$\Delta d(x) + nH(x,k) = \Delta d(x) - \Delta d(y_0) + \Delta d(y_0) + nH(x,k)$$

> $-\nu - (n-1)\mathcal{H}_S(y_0) + nH(x,k)$ (a)
> $-2\nu - (n-1)\mathcal{H}_{\partial\Omega}(y_0) + nH(x,k)$ (b)

$$> 2\nu - nH(y_0, k) + nH(x, k) \tag{c}$$

$$>\nu$$
, (d)

where (a) follows directly from (10), (b) from (9), (c) from (7) and (d) from (8). Using this estimate on (11) we have

$$\begin{aligned} \mathfrak{Q}v &< \frac{\phi'}{(1+\phi'^2)^{1/2}}\nu + \frac{\phi''}{(1+\phi'^2)^{3/2}} \\ &= \frac{1}{(1+\phi'^2)^{3/2}} \left(\phi'(1+\phi'^2)\nu + \phi''\right) \\ &< \frac{1}{(1+\phi'^2)^{3/2}} \left(\phi'^3\nu + \phi''\right). \end{aligned}$$

Let us now define ϕ explicitly by²

$$\phi(t) = \sqrt{\frac{2}{\nu}} \left((a - \epsilon)^{1/2} - (t - \epsilon)^{1/2} \right).$$
(12)

We observe that ϕ satisfies P1–P4 and that $\phi'^{3}\nu + \phi'' = 0$ for each $\epsilon < t < a$. Then, $\mathfrak{Q}v < 0$ in Ω_{ϵ} . From proposition 10 we deduce that

$$u \le v = \max\left\{k, \sup_{\partial B_a(y_0)\cap\Omega} u\right\} + \phi(\epsilon) \text{ in } S_\epsilon \cap B_a(y_0).$$

In particular,

$$u(\gamma_{y_0}(\epsilon)) \le \max\left\{k, \sup_{\partial B_a(y_0)\cap\Omega} u\right\} + \sqrt{\frac{2}{\nu}} \left((a-\epsilon)^{1/2}\right),$$

²See also [10, \$14.4] and [12, Th. 4.1 p. 40].

where $\gamma_{y_0}(\epsilon) = \exp_{y_0}(\epsilon N_{y_0})$. Since this estimate holds for each $0 < \epsilon < a$, we can pass to the limit as ϵ goes to zero to obtain

$$u(y_0) \le \max\left\{k, \sup_{\partial B_a(y_0) \cap \Omega} u\right\} + \sqrt{\frac{2a}{\nu}}.$$
(13)

Step 2.

Let $\rho(x) = \operatorname{dist}(x, y_0)$ for $x \in \Omega' = \Omega \setminus B_a(y_0)$ and $\delta = \operatorname{diam}(\Omega)$. Choose $\psi \in \mathscr{C}^2(a, \delta)$ satisfying

P5.
$$\psi(\delta) = 0$$
, P6. $\psi' \le 0$, P7. $\psi'' \ge 0$, P8. $\psi'(a) = -\infty$,

We also need that $\frac{c\psi'^3}{t} + \psi'' \leq 0$ in (a, δ) , where c is a constant to be choose later on. Let $w = \sup_{\partial \Omega \setminus B_a(y_0)} u + \psi \circ \rho$. We remind that $\rho \in \mathscr{C}^2(M \setminus (\operatorname{cut}(y_0) \cup \{y_0\}))$, so $w \in \mathscr{C}^2(\Omega \setminus B_a(y_0))$. The idea is to use proposition 10 again. We note that $w \geq u$ in $\partial \Omega \setminus B_a(y_0)$. Also, if N is the normal to $\partial B_a(y_0) \cap \Omega$ inwards Ω' , we have for each $x \in \partial B_a(y_0) \cap \Omega$ that

$$\frac{\partial w}{\partial N}(x) = \langle \nabla w(x), N \rangle = \langle \psi'(\rho(x)) \nabla \rho(x), \nabla \rho(x) \rangle = \psi'(a) = -\infty.$$

For w we have

$$\mathfrak{Q}w = \frac{\psi'}{(1+\psi'^2)^{1/2}}\Delta\rho + \frac{\psi''}{(1+\psi'^2)^{3/2}} - nH(x,w).$$

Since $H \ge 0$, it follows

$$\mathfrak{Q}w \le \frac{\psi'}{(1+\psi'^2)^{1/2}}\Delta\rho + \frac{\psi''}{(1+\psi'^2)^{3/2}}.$$

In any of the hypothesis (a) or (b), the radial geodesics issuing from y_0 and intercepting Ω do not contain conjugate points to y_0 (see [15, Th. 6.5.6 p. 151], [6, Th. p. 107]). Then the Laplacian comparison theorem [11, Th. A p. 19] can be use to estimate $\Delta \rho$.

Under the hypothesis (a) we compare M with \mathbb{R}^n to obtain

$$\Delta \rho(x) \ge \frac{n-1}{\rho(x)}.$$

Under the hypothesis (b) we compare M with the sphere $S_{K_0}^n$ of sectional curvature $K_0 > 0$. In this case we have

$$\Delta \rho(x) \ge (n-1)\sqrt{K_0} \cot\left(\sqrt{K_0}\rho(x)\right).$$

From the second assumption on (b) there also exists $0 < \kappa < \frac{\pi}{2\sqrt{K_0}}$ such that $\operatorname{dist}(x, y_0) \leq \frac{\pi}{2\sqrt{K_0}} - \kappa$, for each $x \in \overline{\Omega}$. Thus, for each $x \in \Omega \setminus B_a(y_0)$, there

exists a unique normal minimizing geodesic β such that $\beta(0) = y_0$ and $\beta(t_0) = x$, where $t_0 \leq \frac{\pi}{2\sqrt{K_0}} - \kappa$. Let's define the function $\xi(t) = \sqrt{K_0} t \cot(\sqrt{K_0} t)$ for t > 0. We note that ξ is decreasing and $\xi\left(\frac{\pi}{2\sqrt{K_0}}\right) = 0$. Then,

$$\xi(t) \ge \xi\left(\frac{\pi}{2\sqrt{K_0}} - \kappa\right) > 0, \ \forall t \in \left(0, \frac{\pi}{2\sqrt{K_0}} - \kappa\right].$$

Consequently,

$$\rho(x)\Delta\rho(x) \ge (n-1)C,$$

where

$$C = \sqrt{K_0} \left(\frac{\pi}{2\sqrt{K_0}} - \kappa \right) \cot \left(\sqrt{K_0} \left(\frac{\pi}{2\sqrt{K_0}} - \kappa \right) \right) > 0.$$

Thus $\Delta \rho(x) \geq \frac{c}{\rho}$, where c = n - 1 in the case (a) and c = (n - 1)C in the case (b).

Then, we have

$$\begin{split} \mathfrak{Q}w &\leq \frac{\psi'}{(1+\psi'^2)^{1/2}} \cdot \frac{c}{\rho} + \frac{\psi''}{(1+\psi'^2)^{3/2}} \\ &= \frac{1}{(1+\psi'^2)^{3/2}} \left(\frac{c}{\rho}\psi'(1+\psi'^2) + \psi''\right) \\ &< \frac{1}{(1+\psi'^2)^{3/2}} \left(\frac{c}{\rho}\psi'^3 + \psi''\right). \end{split}$$

Let us define ψ as 3

$$\psi(t) = \left(\frac{2}{c}\right)^{1/2} \int_t^\delta \left(\log\frac{r}{a}\right)^{-1/2} dr.$$
(14)

Such a function satisfies P5–P8, and also $\frac{c}{t}\psi'(t)^3 + \psi''(t) < 0$ for each $a < t < \delta$. Then, $\mathfrak{Q}w < 0 \text{ em } \Omega'$.

From proposition 10 we can conclude that $u \leq w$ in $\partial B_a(y_0) \cap \Omega$, where

$$\sup_{\partial B_a(y_0)\cap\Omega} u \le \sup_{\partial\Omega\setminus B_a(y_0)} u + \psi(a).$$
(15)

We observe that, in fact, this estimate holds for each a such that $\partial B_a(y_0) \cap \Omega$ is connected.

We use (15) in (13) from step 1, so

$$u(y_0) \le \max\left\{k, \sup_{\partial\Omega\setminus B_a(y_0)}u\right\} + \psi(a) + \sqrt{\frac{2a}{\nu}}.$$

It is easy to see that $\lim_{a\to 0} \psi(a) = 0$. Hence, for each $\varepsilon > 0$, a can be choose small enough to satisfy

$$\psi(a) + \sqrt{\frac{2a}{\nu}} < \varepsilon. \qquad \Box$$

 $^{{}^{3}}See also [10, \$14.4]$

Remark 12. In the case where H = H(x),

$$u(y_0) < \sup_{\partial \Omega \setminus B_a(y_0)} u + \varepsilon_1$$

where a is chosen as before.

At last we are able to prove theorem 1.

Proof of the main non-existence theorem. Obviously we can suppose that $H \ge 0$. Then,

$$(n-1)\mathcal{H}_{\partial\Omega}(y_0) < nH(y_0,k)$$

for some $k \in \mathbb{R}$ since H is non-decreasing in z. Let $\varepsilon > 0$ and $\varphi \in \mathscr{C}^{\infty}(\overline{\Omega})$ such that $\varphi = k$ in $\partial \Omega \setminus B_a(y_0)$ and $\varphi(y_0) = k + \varepsilon$. Hence, no solution of equation (1) in Ω could have φ as boundary values because such a function does not satisfy the estimate (6).

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