

“non-hiperbolicities”

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Brasil-França, IMPA, 2009

thanks:

to the [Brazil-France Cooperation in Mathematics](#),

for the long-lasting support....

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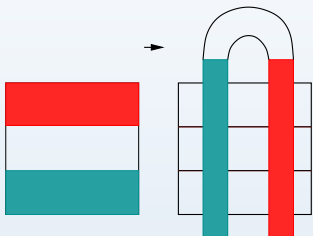
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horseshoes

hyperbolic systems

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symbolic dynamics (i)

Each orbit in the horseshoe Λ is represented by a sequence of **0** (iterate in the red rectangle) and **1** (iterate in the blue rectangle):

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symbolic dynamics (conjugation to shifts)

$\Sigma = \{0, 1\}^{\mathbb{Z}}$, with some metric...

$\sigma: \Sigma \rightarrow \Sigma, \quad (x_i) \mapsto (y_i), \quad y_i = x_{i+1}.$

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commutative diagram: h is a homeomorphism (conjugation).

$$\begin{array}{ccccc}
 \Sigma & \rightarrow & \sigma & \rightarrow & \Sigma \\
 h \downarrow & & & & \downarrow h \\
 \Lambda & \rightarrow & f & \rightarrow & \Lambda
 \end{array}$$

translate shift properties (symbolic dynamics) to the ambient dynamics:

- mixing, transitivity (dense orbits, recurrences....),
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directions corresponding to uniform contraction (**stable**) and expansion (**unstable**).

$f: M \rightarrow M$, diffeo., M compact and closed,

Λ : f -invariant ($f(\Lambda) = \Lambda$) compact set.

hyperbolic set:

$$T_x M = E^s \oplus E^u,$$

Df -invariant and constants $C > 0$ and $\lambda < 1$ with

$$|Df^m(v^s)| \leq C \lambda^m |v^s|, \quad |Df^{-m}(v^u)| \leq C \lambda^m |v^u|,$$

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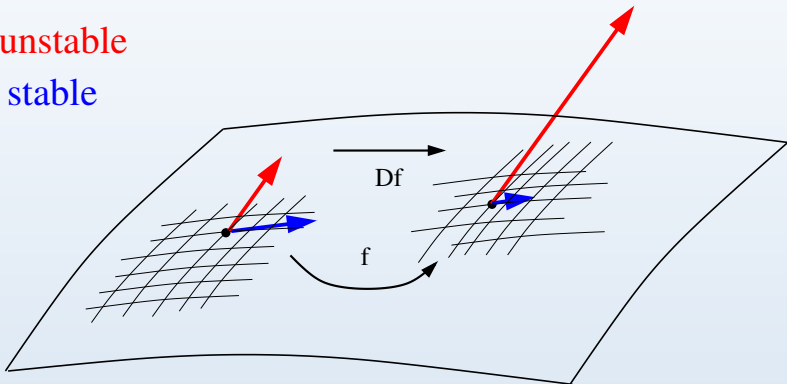
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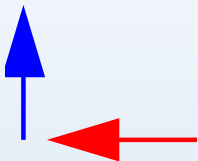
hyperbolicity

unstable
stable



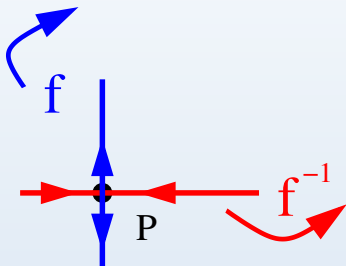
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generation of hyperbolic sets (horsesoos)



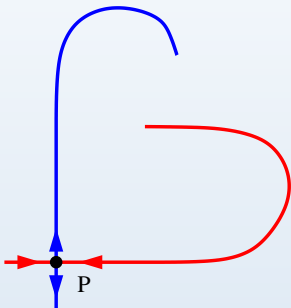
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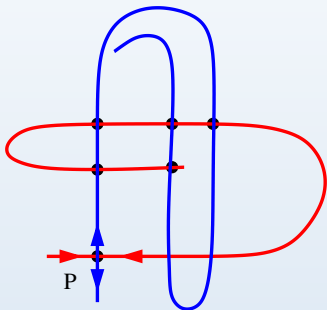
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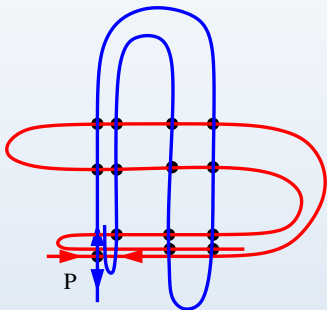
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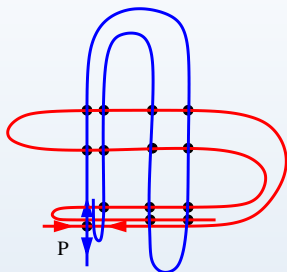


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$H(P)$ **homoclinic class of P** : closure of the transverse intersections its invariant (stable and unstable) manifolds.

- **mixing, transitivity** (dense orbits, recurrences....),
- **infinitely many periodic points,**
- **in some cases $H(P)$ fails to be hyperbolic...**

hyperbolic summary

general facts

- There is a complete theory of hyperbolic systems: geometric, topological, and ergodic (probabilistic) aspects.
- Nonhyperbolic systems are quite frequent and many of them exhibit “some (weak) hiperbolicity”
- non-hyperbolicities: non-uniform, partial, singular, dominated splittings....
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Dichotomy: hyperbolicity versus cycles

cycles:

- homoclinic tangencies ($\dim \geq 2$),
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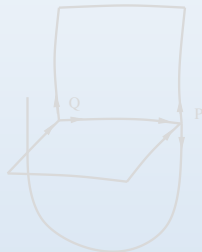


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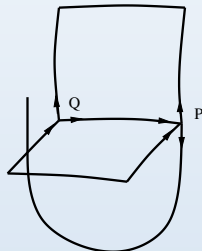
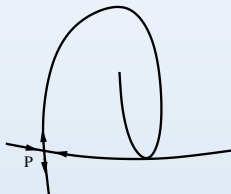


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some results

the conjecture holds for

- circle maps (Peixoto),
- C^1 surface diffeomorphisms (Pujals-Sambarino),
- C^1 tame diffeomorphisms (Bonatti-D.).

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Those having stably finitely many homoclinic classes.

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- uniform rate of expansion and contraction,
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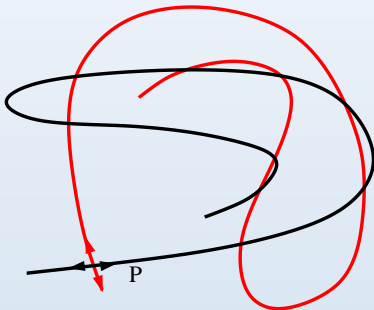
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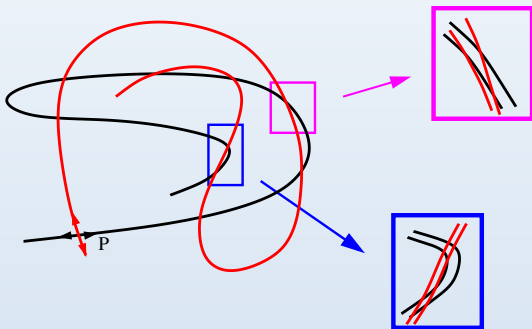
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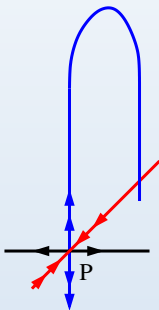
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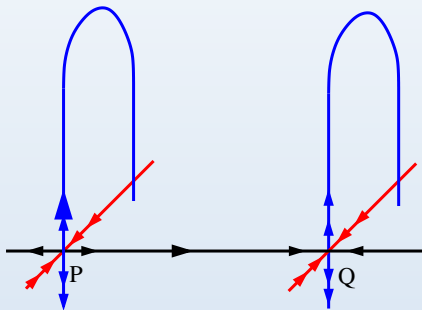
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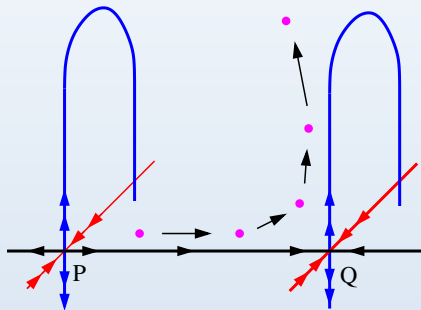
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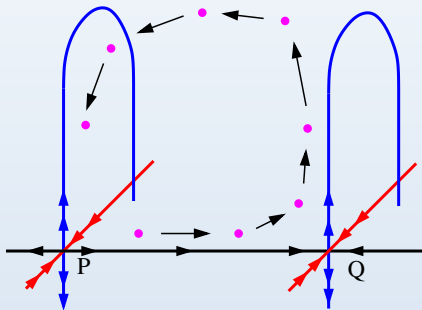
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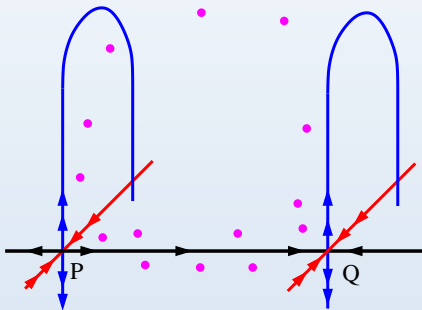
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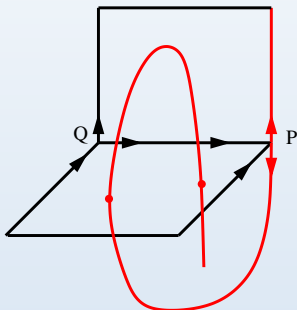
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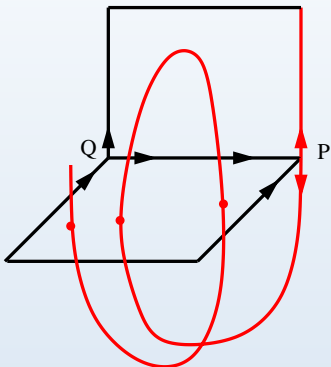
non-hyperbolic homoclinic classes

$H(P)$ may contain saddles of **index** (dimension of stable bundle) different from the one of P . Typical non-dynamical feature.



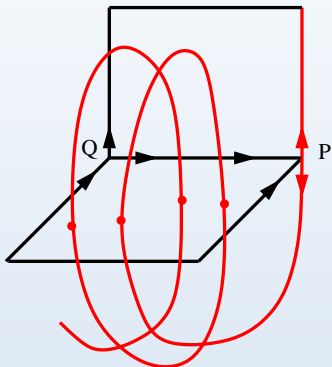
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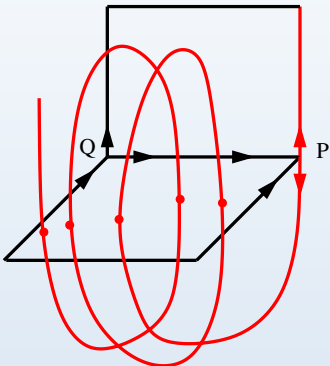
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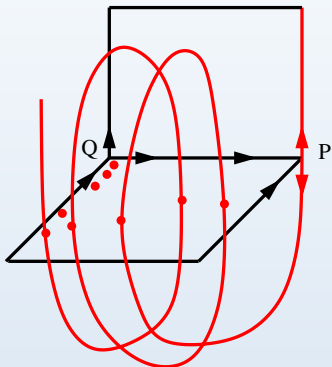
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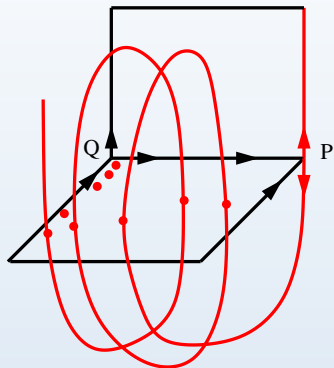


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caution: a homoclinic class whose saddles have all the same index may be non-hyperbolic....

non-critical model: skew products

f_0, f_1 circle maps,

f_0 East-West map, f_1 irrational rotation.



$\sigma: \{0, 1\}^{\mathbb{Z}} \rightarrow \{0, 1\}^{\mathbb{Z}}$ horseshoe (shift map).

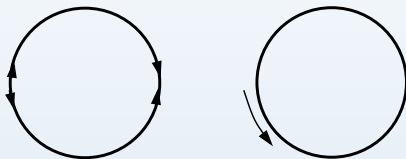
skew-product (partially hyperbolic map)

$$F: \{0, 1\}^{\mathbb{Z}} \times S^1 \rightarrow \{0, 1\}^{\mathbb{Z}} \times S^1, \quad F(\alpha, x) = (\sigma(\alpha), f_{\alpha_0}(x)).$$

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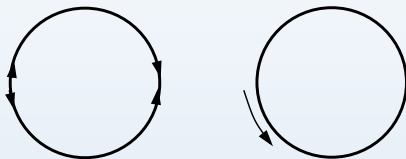
skew-product (partially hyperbolic map)

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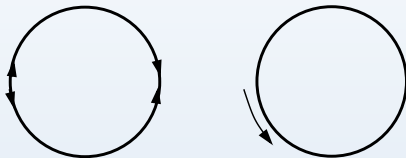
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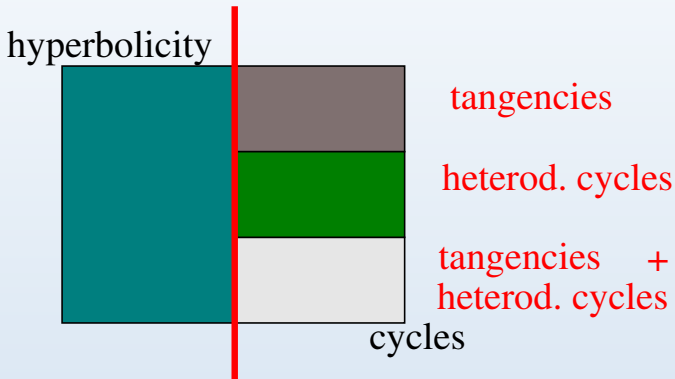
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dichotomies and more....

hyperbolicity and cycles

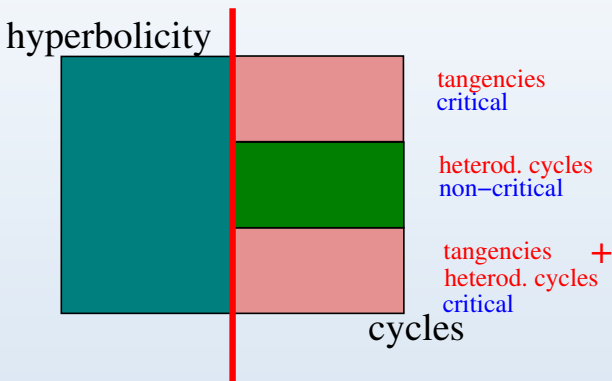
$\text{Diff}^1(M)$



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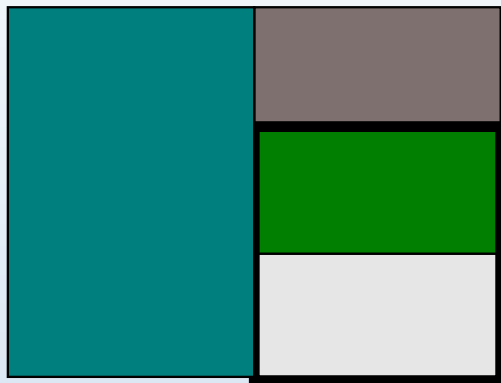
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robust het. cycles

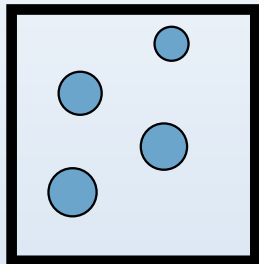
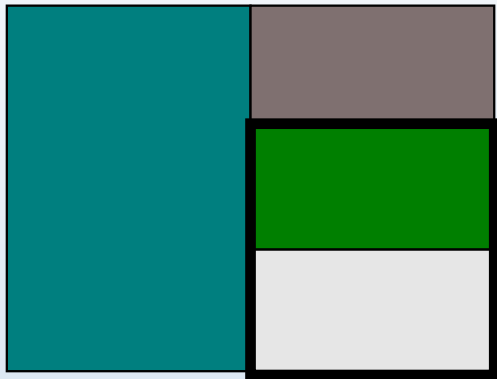
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heterodimensional cycles associated to hyperbolic sets

Λ and Σ hyperbolic sets, different indices

$$W^s(\Lambda) \cap W^u(\Sigma) \neq \emptyset \quad W^u(\Lambda) \cap W^s(\Sigma) \neq \emptyset.$$

similarly for **homoclinic tangencies**.

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every g close to f has a cycle.

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generically, periodic points are hyperbolic and their invariant manifolds are in general position (transversality).

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- bifurcations of periodic orbits (saddle-node, flip, Hopf),
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- cycles,
- Newhouse-like phenomena: super-exponential growth of the number of periodic points,
- non-hyperbolic ergodic measures with large support,
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Which dynamical features are typical of each form of non-hyperbolicity?

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μ **ergodic** measure of f : $\mu(f^{-1}(A)) = \mu(A)$ implies $\mu(A) = 0, 1$,

there are Λ of full μ -measure,

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$f: X \rightarrow X$, homeomorphism,

(X, f) has a **symbolic extension** if there exists a subshift (finitely many symbols) (Y, σ) and a continuous surjective map $\pi: Y \rightarrow X$ such that

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$f: M \rightarrow M$, diffeo., M compact and closed,

Λ : f -invariant ($f(\Lambda) = \Lambda$) compact set.

dominated splitting: $T_\Lambda M = E \oplus F$, Df -invariant and there is m with

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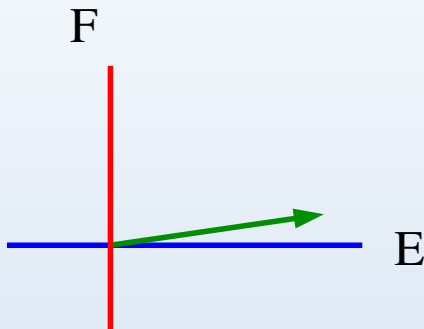
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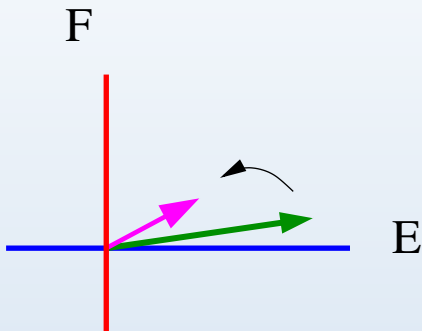
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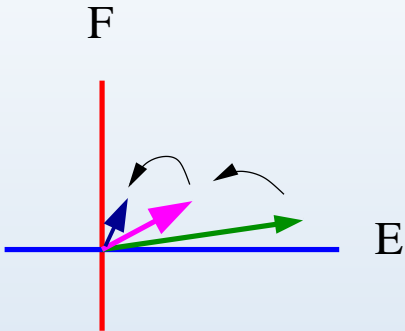
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for simplicity: **dimension of M is three**

possibilities for the finest dominated splitting of a homoclinic class.

- **non-critical case:** three bundles $E^s \oplus E^c \oplus E^u$, E^s and E^u hyperbolic.
- **critical case:**
 - two bundles: $E^s \oplus E^{cu}$ or $E^{cs} \oplus E^u$, E^s and E^u one-dimensional and hyperbolic.
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C^1 generic setting (homoclinic classes with saddles of different indices):

non-hyperbolicity **always** implies:

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further information, non-critical case

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summarizing table

dimension three:

dynamics/splitting	3 bundles	2 bundles	non-exist.
• Robust tangencies	No	Yes	Yes
• Robust het. cycles	Yes	Yes	Yes
• non-hyperbolic measures	Yes	Yes	Yes
- full support	Yes	Yes?	Yes?
- # zero exponents	1	2?	3?
• symbolic extensions	Yes	No	No
• ∞ -sinks/sources	No	depend	Yes